

Introduction to Netlogo

Agent-based simulation

Netlogo

Modeling complex systems

- Programmable modeling environment for simulating natural and social phenomena
 - Well suited for modeling complex systems evolving over time
 - Hundreds or thousands of independent agents operating concurrently
 - Exploring the connection between the micro-level behavior of individuals and the macro-level patterns that emerge from the interaction of many individuals

Netlogo

Modeling complex systems

- Easy-to-use application development environment
 - creating custom models and quickly testing hypotheses about self-organized systems
 - simple scripting language
 - user-friendly graphical interface
 - runs on JVM

Wilensky, U. (1999). NetLogo. <http://ccl.northwestern.edu/netlogo/>. Center for Connected Learning and Computer-Based Modeling, Northwestern University, Evanston, IL

Netlogo

Practical Info

- Download link:
 - <http://ccl.northwestern.edu/netlogo/download.shtml>
 - Launch Netlogo through command line:
 - `$ /{netlogo_download_folder}/netlogo.sh`
- Online doc:
 - <https://ccl.northwestern.edu/netlogo/docs/>
- Book for agent-based modeling (special focus on Netlogo):
 - <http://www.intro-to-abm.com/>

Netlogo

History snapshot

- LOGO (Papert & Minsky, 1967)
 - theory of education based on Piaget’s constructionism (“hands-on” creation and test of concepts)
 - simple language derived from LISP
 - turtle graphics and exploration of “micro-worlds”
- StarLogo (Resnick, 1991), MacStarLogo, StarLogoT
 - agent-based simulation language
- NetLogo (Wilensky, 1999)
 - further extending StarLogo (continuous turtle coordinates, cross-platform, networking, etc.)

Netlogo

The world of Netlogo

- NetLogo is a 2-D world made of 4 kinds of agents:
 - *Patches* - make up the background or “landscape”
 - *Turtles* - move around on top of the patches
 - *Links* - connect two turtles
 - *The Observer* - oversees everything going on in the world

Graphical Interface

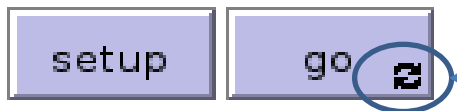
Controls

- Controls allow to run and manage the flow of execution

- Buttons: initialize, start, stop, step through the model

- “Once” button execute one action

- “Forever” button repeat the same action until pressed again



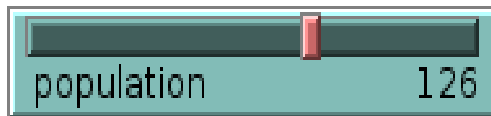
- Functions with the name of the buttons specify the action executed on click

- Command centre: ask agents to execute specific commands “on the fly”

Graphical Interface

Settings

- Settings allow to modify parameters
 - Sliders: adjust a quantity from *min* to *max* by an *increment*



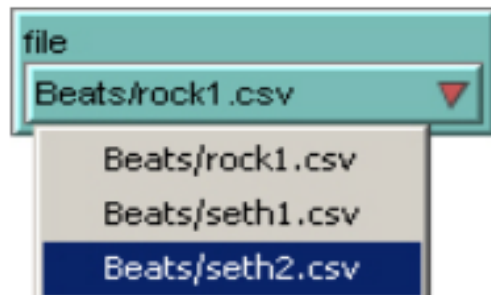
population = 126

- Switches: set a Boolean variable



incentivi_installazione? = false

- Choosers: set a value from a list



file = "Beats/seth2.csv"

Graphical Interface

Views

- Views allow to display information
 - Monitors display the current value of variables

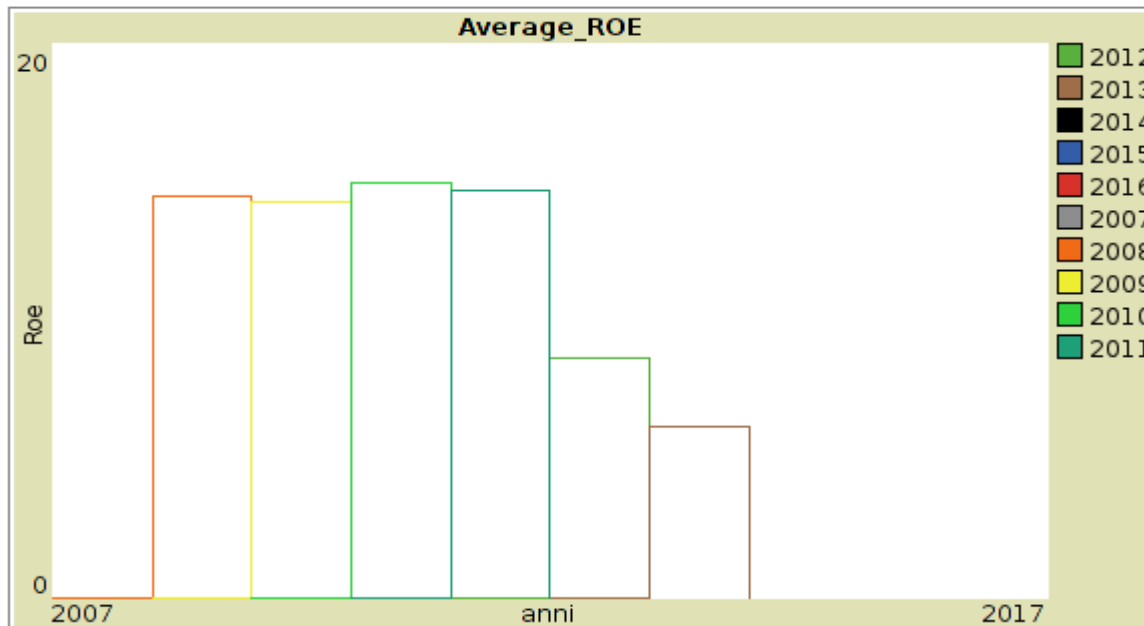
kw INSTALLATI 2013
314

INCENTIVI INSTALLAZIONE 2013
0

INCENTIVI 2013
752604

TOTALE SPESA 2013
752604

- Plots: display the history of a variable's value



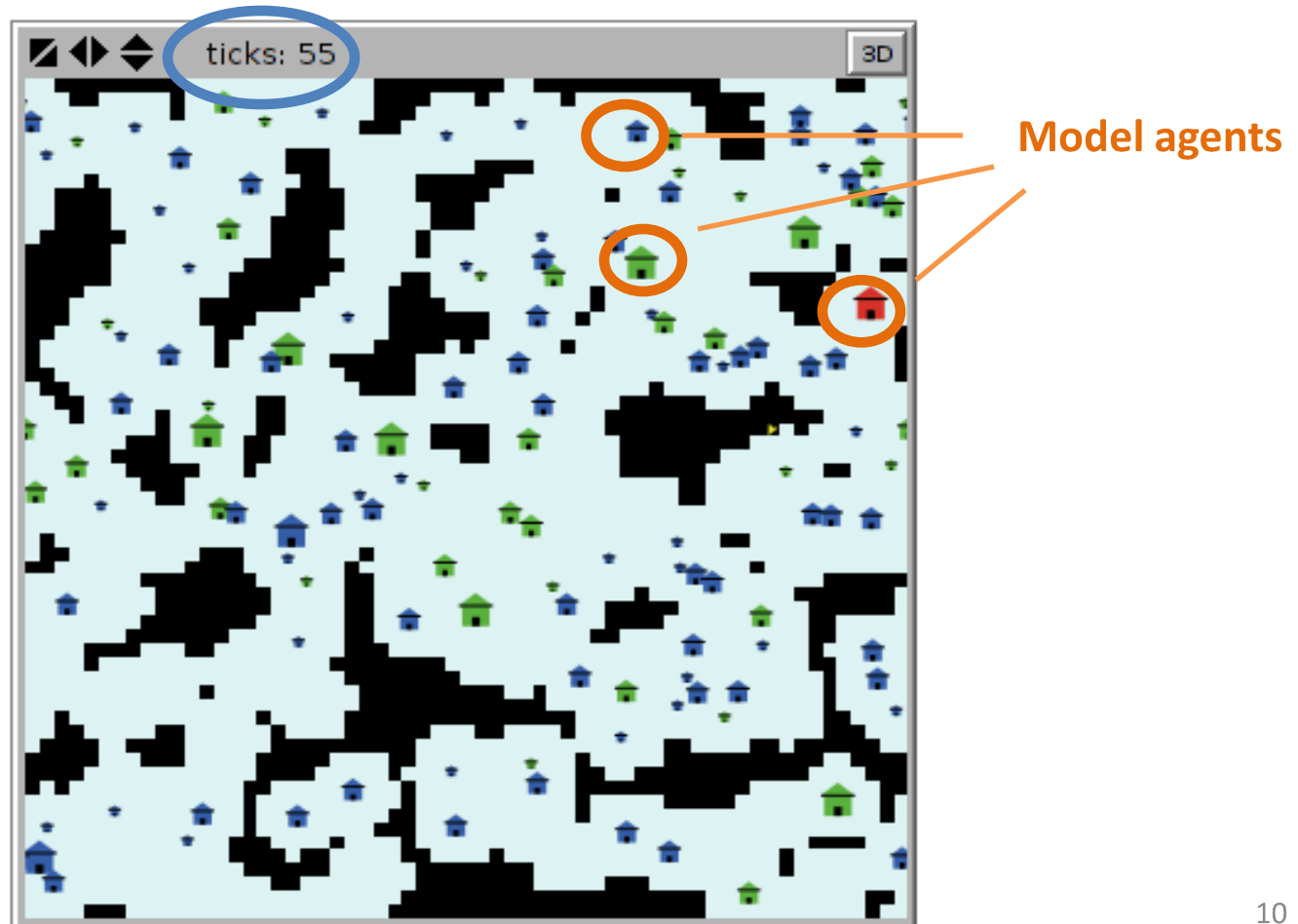
- Output text areas, log text info

Graphical Interface

Views

- Graphic window, the main view of the 2-D Netlogo world

Model evolution
(based on discrete
time-steps)



Programming Concepts

Agents

- Agents carry out their activity, all simultaneously
 - Patches don't move, form a 2-D wrap-around grid, have integer coordinates ($pxcor,pycor$)
 - Turtles move on top of patches (not necessarily in their centre), have decimal coordinates ($xcor,ycor$) and orientation (*heading*)
 - Observer can create new turtles, can have read/write access to all the agents and variables

Programming Concepts

Procedures & Functions

- Commands (“to” keyword)
 - Action for the agents to carry out (“void” functions)
 - Example with 2 input arguments:

```
to draw-polygon [ num-sides size ]  
  pd      ;; pen down, draw  
  repeat num-sides  
  [      fd size      ;; forward 'size' steps  
    rt (360 / num-sides) ] ;; rotate  
end
```

Programming Concepts

Procedures & Functions

- Reporters (“to-report”)
 - Report a result value
 - Example with 1 input arguments:

```
to-report absolute-value [ number ]  
  if-else number >= 0  
  [ report number ]  
  [ report 0 - number ]  
end
```

- Primitives
 - Built-in command or reporters
 - Some have an abbreviated form (create-turtle <--> crt)
- Procedures
 - Custom commands or reporters (user made)

Programming Concepts

Variables

- Variables – places to store values
 - Global variables: only one value for the variable and every agent can access it
 - Turtle and Patch variables: each turtle/patch has its own value for every turtle/patch variable
 - Local variables: defined and accessible only inside a procedure (scope=narrowest square brackets or procedure itself)

Programming Concepts

Variables

- Built-in variables
 - Ex. turtle variables: color, xcor, ycor, etc.
 - Ex. Patch variables: pcolor, pxcor, etc.
- Custom variables
 - Defining global variables
`global [clock]`
 - Defining turtle/patch variables
`turtles-own [energy speed]`
`patches-own [friction]`

Programming Concepts

Variables

- Custom variables
 - Defining global variables
 - Defining turtle/patch variables
 - Defining local variables:
 - **let variable value**
 - Creates a new local variable and gives it the desired value
- ```
to swap-colors [t1 t2]
 let temp color-of t1
```
- Setting a variable values (after its definition):
    - **set variable value**



# Programming Concepts

## Ask

- Ask – specify commands to be run by turtles or patches
  - Asking all turtles  
`ask turtles [ ... ]`
  - Asking all patches
  - Asking  $N$  turtles  
`ask n-of N turtles [ ... ]`
- Observer code *cannot* be inside any “ask” block

# Programming Concepts

## Variables

- Setting variables
  - Setting the color of all turtles

```
ask turtles [set color red]
```
  - Setting the color of all patches

```
ask patches [set pcolor red]
```
  - Setting the color of the patches under the turtles

```
ask turtles [set pcolor red]
```
  - Setting the color of one turtle (identify by ID)

```
ask turtle 5 [set color green]
```
  - or

```
set color-of turtle 5 green
```
  - Setting the color of one patch (identified with coordinates)

```
ask patch 2 3 [set pcolor green]
```

# Programming Concepts

## Agent sets

- Agent set, definition of a subset of agents (not a keyword)
  - All blue turtles  
`turtles with [ color = blue ]`
  - All blue turtles on the patch of the current caller (patch or turtle)  
`turtles-here with [ color = blue ]`
  - All turtles less than 5 patches away from caller  
`turtles in-radius 3`
  - The 4 patches to the east, north, west and south of the caller  
`patches at-points [[1 0] [0 1] [-1 0]  
[0 -1]]`



# Programming Concepts

## Breeds

- *Breed*, a “natural” kind of agent set (other species than turtle)

```
breed [wolves sheep]
```

- A new breed comes with automatically derived primitives:

```
create-<breed>
```

```
create-custom-<breed>
```

```
<breed>-here
```

```
<breed>-at
```

- The breed is a turtle variable

```
ask turtles 5 [if breed=sheep]
```

- A turtle agent can change breed

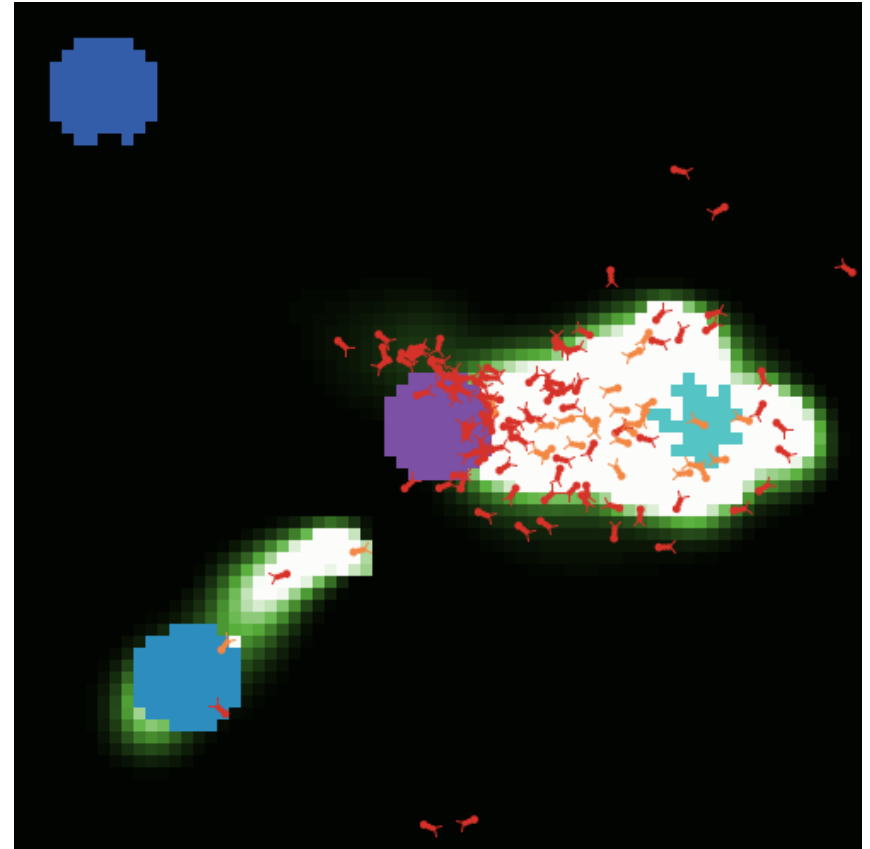
```
ask turtles 5 [set breed sheep]
```

# Exercise 1

## Basic Ants Model

- Very simple model as a first “hands-on” experience
- A colony of ants forages for food
  - Though each ant follows a set of simpler rules, the colony as a whole act in a sophisticated way

*Wilensky, U. (1997). NetLogo Ants model. <http://ccl.northwestern.edu/netlogo/models/Ants>. Center for Connected Learning and Computer-Based Modeling, Northwestern University, Evanston, IL.*



# Exercise 1

## Ants Model

- When an ant finds a piece of food, it carries the food back to the nest, dropping a chemical as it moves
- When other ants “sniff” the chemical, they follow the chemical toward the food
- As more ants carry food to the nest, they reinforce the chemical trail

# Exercise 1

## Model Usage

- Click the SETUP button to set up the ant nest (in violet, at center) and three piles of food then click the GO button to start the simulation.
  - The chemical is shown in a green-to-white gradient.
- The EVAPORATION-RATE slider controls the evaporation rate of the chemical. The DIFFUSION-RATE slider controls the diffusion rate of the chemical.
- If you want to change the number of ants, move the POPULATION slider before pressing SETUP



# Exercise 1

## Things to notice

- The ant colony generally exploits the food source in order, starting with the food closest to the nest, and finishing with the food most distant from the nest
- It is more difficult for the ants to form a stable trail to the more distant food, since the chemical trail has more time to evaporate and diffuse before being reinforced

# Exercise 1

## Things to notice

- Once the colony finishes collecting the closest food, the chemical trail to that food naturally disappears, freeing up ants to help collect the other food sources.
  - The more distant food sources require a larger “critical number” of ants to form a stable trail.
- The consumption of the food is shown in a plot.
  - The line colors in the plot match the colors of the food piles.

# Exercise 1

## Model Extensions

1. Try different placements for the food sources
  - What happens if two food sources are equidistant from the nest?
2. In this project, the ants use a “trick” to find their way back to the nest: they follow the “nest scent.”
  - Real ants use a variety of different approaches to find their way back to the nest.
  - Try to implement some alternative strategies.
3. In the uphill-chemical procedure, the ant “follows the gradient” of the chemical. That is, it “sniffs” in three directions, then turns in the direction where the chemical is strongest.
  - Try variants of the uphill-chemical procedure, changing the number and placement of “ant sniffs.”

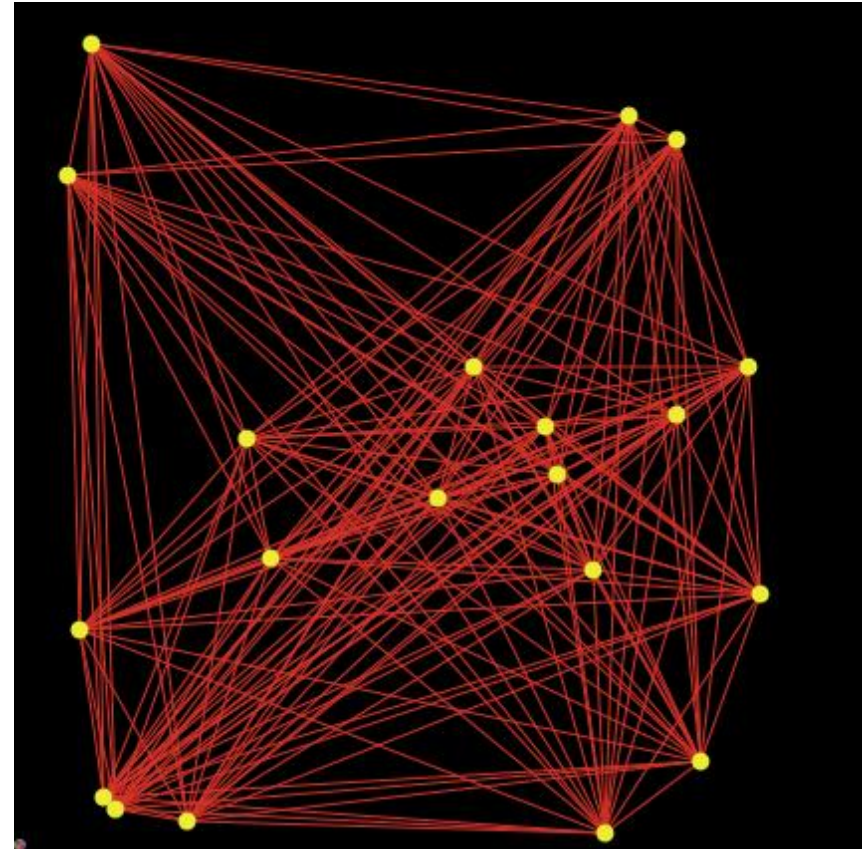
# Exercise 2

## Ant Colony Optimization e TSP

- Goal: implementing the Ant System algorithm<sup>1</sup> and use it to solve the Traveling Salesman Problem
- Based on the observation of ants behaviour
  - Positive feedback based on pheromone tracks which reinforce the best solution components

<sup>1</sup> Dorigo, M., Maniezzo, V., and Colorni, A., *The Ant System: Optimization by a colony of cooperating agents*. *IEEE Transactions on Systems, Man, and Cybernetics Part B: Cybernetics*, Vol. 26, No. 1. (1996), pp. 29-41.

<http://citeseer.ist.psu.edu/dorigo96ant.html>



# Exercise 2

## Ant Colony

- As you already know
  - Ants leave a pheromone trail while going from the nest to food sources (and vice versa)
  - Ants tend to choose (with higher probability) routes with greater amount of pheromones
  - Cooperative interaction which leads to an emergent behaviour, that is finding the shortest path

# Exercise 2

## ACO

- Probabilistic model (*pheromone* model) used to recreate the pheromone trails left by ants
- Ants incrementally build the component of a solution
- Ants perform stochastic steps on a fully connected graph (*construction graph*)
- Constraints used to obtain a feasible solution

# Exercise 2

## ACO and TSP

- A possible model for TSP:
  - The graph nodes are the city to visit (the components of a solution)
  - The edges are the connections between the cities
  - A solution is a Hamiltonian circuit in the graph
  - Constraints are used to avoid loops, so that an ant can visit a city exactly once

# Exercise 2

## Information sources

- Edges or vertexes (or both) have two information:
  - Pheromone  $\tau$ , which stands in for natural trail left by ants and represents the long term memory of ants in relation to the global search process
  - Heuristic value  $\eta$ , i.e. the a priori knowledge on the problem



# Exercise 2

## ACO System

- The ants follow a path on the construction graph and build a solution
- They used a transition (probabilistic) rule to choose the next node to visit
- Both pheromone and heuristic are taken into account
- Pheromone values are adjusted based on the quality of the solution found

# Introduction to Netlogo

End

Additional info, questions, etc..

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